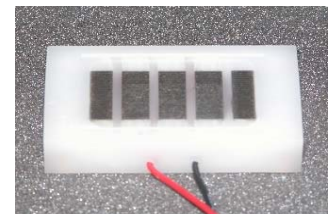
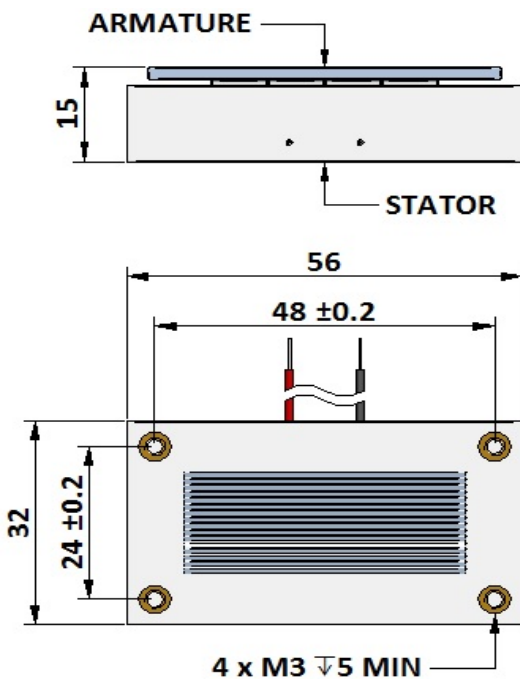


P_{100} is the continuous (100% ED) excitation power at which the coil attains temperature T_{max} with the part mounted to a massive heatsink at 20°C

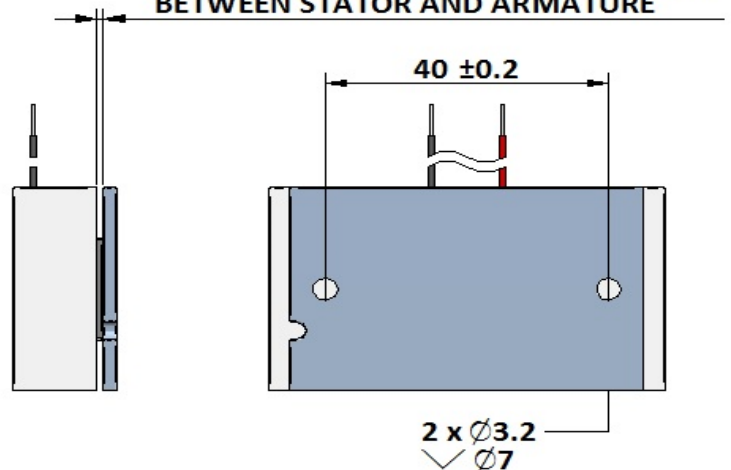
| | | | |
|-----------|-------|-------------|------|
| P_{100} | 2.5 W | Total Mass | 86 g |
| T_{max} | 80 °C | Moving Mass | 30 g |

| Model No. | Resistance R_{20} | Inductance |
|-----------|------------------------|------------|
| HAP56-10 | 10.0 Ω | 0.6 mH |

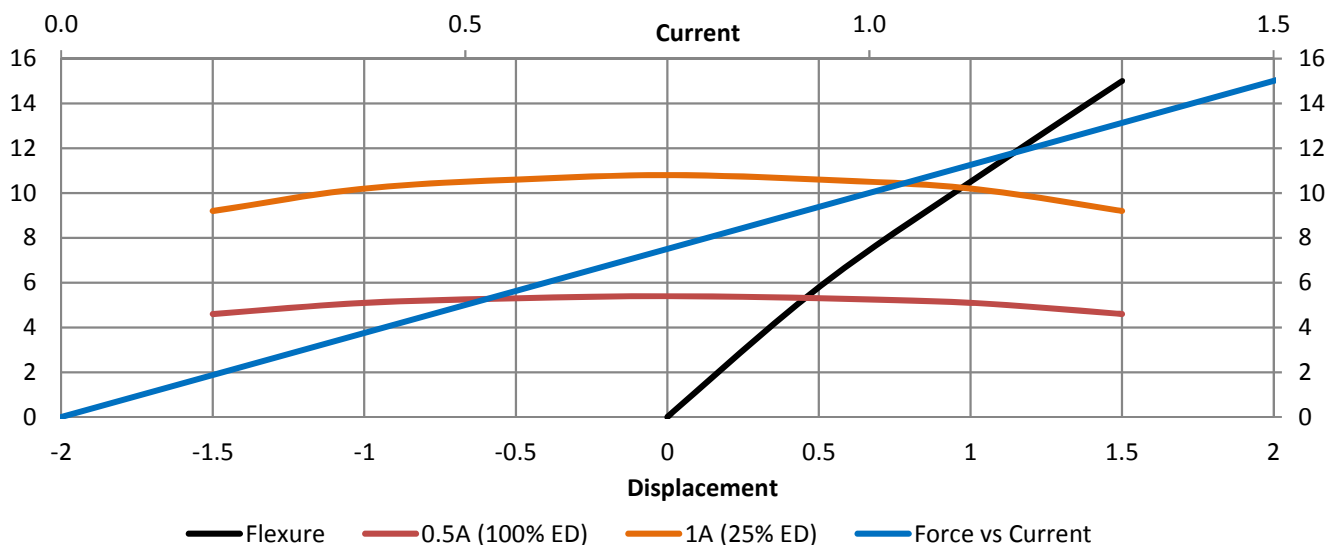
The HAP56 actuator is designed to generate linear vibration when energised with an AC signal. It will develop a high force over displacement of 3-4mm for excitation power of only a few watts. It can be used to generate tactile feedback for MMI applications, or as a motion generator for linear conveyors / component feeders



AIRGAP 0.8 ±0.2 MUST BE MAINTAINED BETWEEN STATOR AND ARMATURE



Typical Force Characteristic





GEEPLUS

Vibration Actuator



P₁₀₀ **2.5 W** **Total Mass** **150 g**

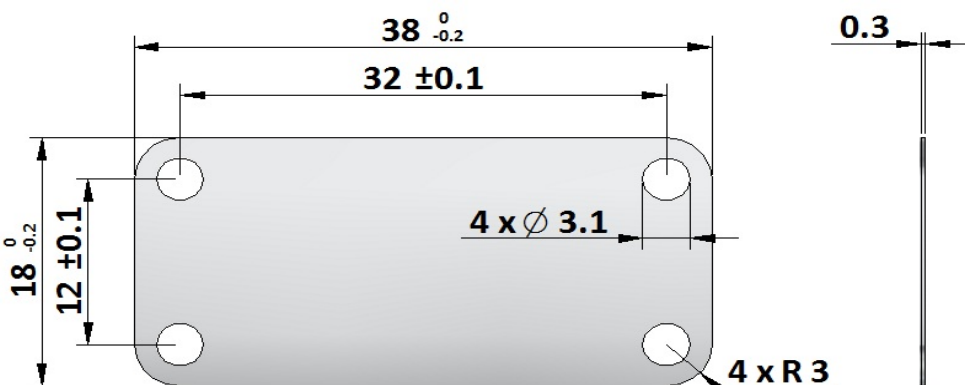
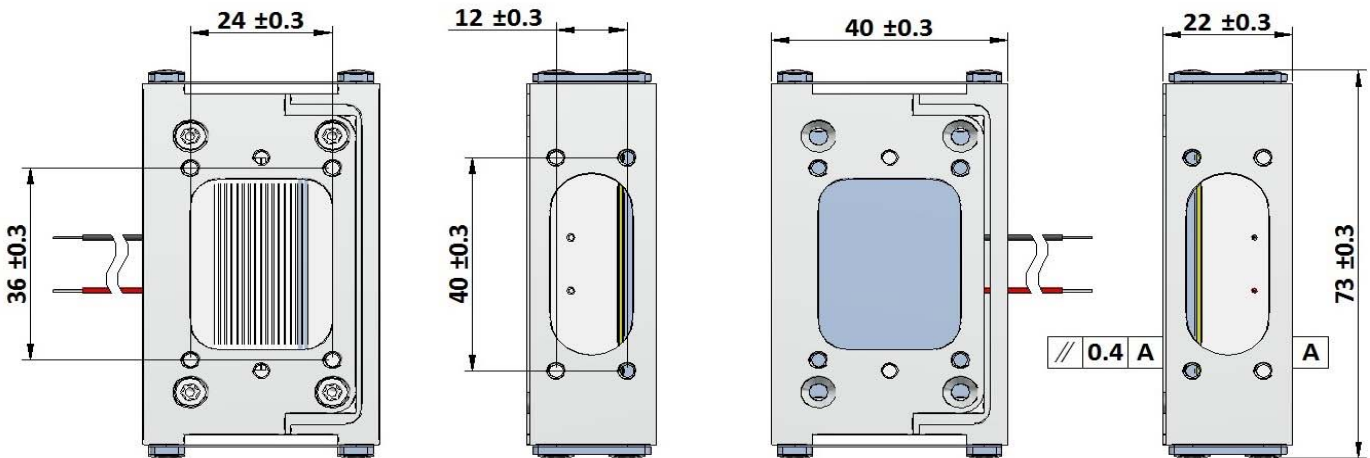
T_{max} **80 °C** **Moving Mass** **52 g**

P100 is the continuous (100% ED) excitation power at which the coil attains temperature Tmax with the part mounted to a massive heatsink at 20°C

The VIBRO1 incorporates a HAP56 actuator in an easily mounted cast body with steel flexures for support. The VIBRO1 facilitates simple implementation of small vibratory assemblies.

| Model No. | Resistance R ₂₀ | Inductance |
|-----------|-------------------------------|------------|
| VIBRO1-10 | 10.0 Ω | 0.6 mH |

4 x mounting holes in each face are M3 x P0.5, maximum 3 deep



87-1044

The steel flexure 87-1044 can be used to provide support to vibrating loads driven by the VIBRO1 or HAP56 actuator devices. Either end should be securely clamped between flat surfaces.